

## 67 HAL TSC Generic Driver

### 67.1 TSC Firmware driver registers structures

#### 67.1.1 TSC\_InitTypeDef

##### Data Fields

- *uint32\_t CTPulseHighLength*
- *uint32\_t CTPulseLowLength*
- *uint32\_t SpreadSpectrum*
- *uint32\_t SpreadSpectrumDeviation*
- *uint32\_t SpreadSpectrumPrescaler*
- *uint32\_t PulseGeneratorPrescaler*
- *uint32\_t MaxCountValue*
- *uint32\_t IODefaultMode*
- *uint32\_t SynchroPinPolarity*
- *uint32\_t AcquisitionMode*
- *uint32\_t MaxCountInterrupt*
- *uint32\_t ChannelIOs*
- *uint32\_t ShieldIOs*
- *uint32\_t SamplingIOs*

##### Field Documentation

- ***uint32\_t TSC\_InitTypeDef::CTPulseHighLength***  
Charge-transfer high pulse length This parameter can be a value of [\*\*TSC\\_CTPulseHL\\_Config\*\*](#)
- ***uint32\_t TSC\_InitTypeDef::CTPulseLowLength***  
Charge-transfer low pulse length This parameter can be a value of [\*\*TSC\\_CTPulseLL\\_Config\*\*](#)
- ***uint32\_t TSC\_InitTypeDef::SpreadSpectrum***  
Spread spectrum activation This parameter can be a value of [\*\*TSC\\_CTPulseLL\\_Config\*\*](#)
- ***uint32\_t TSC\_InitTypeDef::SpreadSpectrumDeviation***  
Spread spectrum deviation This parameter must be a number between Min\_Data = 0 and Max\_Data = 127
- ***uint32\_t TSC\_InitTypeDef::SpreadSpectrumPrescaler***  
Spread spectrum prescaler This parameter can be a value of [\*\*TSC\\_SpreadSpec\\_Prescaler\*\*](#)
- ***uint32\_t TSC\_InitTypeDef::PulseGeneratorPrescaler***  
Pulse generator prescaler This parameter can be a value of [\*\*TSC\\_PulseGenerator\\_Prescaler\*\*](#)
- ***uint32\_t TSC\_InitTypeDef::MaxCountValue***  
Max count value This parameter can be a value of [\*\*TSC\\_MaxCount\\_Value\*\*](#)
- ***uint32\_t TSC\_InitTypeDef::IODefaultMode***  
IO default mode This parameter can be a value of [\*\*TSC\\_IO\\_Default\\_Mode\*\*](#)
- ***uint32\_t TSC\_InitTypeDef::SynchroPinPolarity***  
Synchro pin polarity This parameter can be a value of [\*\*TSC\\_Synchro\\_Pin\\_Polarity\*\*](#)
- ***uint32\_t TSC\_InitTypeDef::AcquisitionMode***  
Acquisition mode This parameter can be a value of [\*\*TSC\\_Acquisition\\_Mode\*\*](#)
- ***uint32\_t TSC\_InitTypeDef::MaxCountInterrupt***  
Max count interrupt activation This parameter can be set to ENABLE or DISABLE.

- ***uint32\_t TSC\_InitTypeDef::ChannelIOs***  
Channel IOs mask
- ***uint32\_t TSC\_InitTypeDef::ShieldIOs***  
Shield IOs mask
- ***uint32\_t TSC\_InitTypeDef::SamplingIOs***  
Sampling IOs mask

### 67.1.2 TSC\_IOConfigTypeDef

#### Data Fields

- ***uint32\_t ChannelIOs***
- ***uint32\_t ShieldIOs***
- ***uint32\_t SamplingIOs***

#### Field Documentation

- ***uint32\_t TSC\_IOConfigTypeDef::ChannelIOs***  
Channel IOs mask
- ***uint32\_t TSC\_IOConfigTypeDef::ShieldIOs***  
Shield IOs mask
- ***uint32\_t TSC\_IOConfigTypeDef::SamplingIOs***  
Sampling IOs mask

### 67.1.3 TSC\_HandleTypeDef

#### Data Fields

- ***TSC\_TypeDef \* Instance***
- ***TSC\_InitTypeDef Init***
- ***\_IO HAL\_TSC\_StateTypeDef State***
- ***HAL\_LockTypeDef Lock***

#### Field Documentation

- ***TSC\_TypeDef\* TSC\_HandleTypeDef::Instance***  
Register base address
- ***TSC\_InitTypeDef TSC\_HandleTypeDef::Init***  
Initialization parameters
- ***\_IO HAL\_TSC\_StateTypeDef TSC\_HandleTypeDef::State***  
Peripheral state
- ***HAL\_LockTypeDef TSC\_HandleTypeDef::Lock***  
Lock feature

## 67.2 TSC Firmware driver API description

### 67.2.1 TSC specific features

1. Proven and robust surface charge transfer acquisition principle
2. Supports up to 3 capacitive sensing channels per group
3. Capacitive sensing channels can be acquired in parallel offering a very good response time
4. Spread spectrum feature to improve system robustness in noisy environments
5. Full hardware management of the charge transfer acquisition sequence
6. Programmable charge transfer frequency
7. Programmable sampling capacitor I/O pin
8. Programmable channel I/O pin
9. Programmable max count value to avoid long acquisition when a channel is faulty

10. Dedicated end of acquisition and max count error flags with interrupt capability
11. One sampling capacitor for up to 3 capacitive sensing channels to reduce the system components
12. Compatible with proximity, touchkey, linear and rotary touch sensor implementation

### 67.2.2 How to use this driver

1. Enable the TSC interface clock using `__HAL_RCC_TSC_CLK_ENABLE()` macro.
2. GPIO pins configuration
  - Enable the clock for the TSC GPIOs using `__HAL_RCC_GPIOx_CLK_ENABLE()` macro.
  - Configure the TSC pins used as sampling IOs in alternate function output Open-Drain mode, and TSC pins used as channel/shield IOs in alternate function output Push-Pull mode using `HAL_GPIO_Init()` function.
3. Interrupts configuration
  - Configure the NVIC (if the interrupt model is used) using `HAL_NVIC_SetPriority()` and `HAL_NVIC_EnableIRQ()` function.
4. TSC configuration
  - Configure all TSC parameters and used TSC IOs using `HAL_TSC_Init()` function.

TSC peripheral alternate functions are mapped on AF9.

#### Acquisition sequence

- Discharge all IOs using `HAL_TSC_IODischarge()` function.
- Wait a certain time allowing a good discharge of all capacitors. This delay depends of the sampling capacitor and electrodes design.
- Select the channel IOs to be acquired using `HAL_TSC_IOConfig()` function.
- Launch the acquisition using either `HAL_TSC_Start()` or `HAL_TSC_Start_IT()` function. If the synchronized mode is selected, the acquisition will start as soon as the signal is received on the synchro pin.
- Wait the end of acquisition using either `HAL_TSC_PollForAcquisition()` or `HAL_TSC_GetState()` function or using WFI instruction for example.
- Check the group acquisition status using `HAL_TSC_GroupGetStatus()` function.
- Read the acquisition value using `HAL_TSC_GroupGetValue()` function.

### 67.2.3 Initialization and de-initialization functions

This section provides functions allowing to:

- Initialize and configure the TSC.
- De-initialize the TSC.

This section contains the following APIs:

- [`HAL\_TSC\_Init\(\)`](#)
- [`HAL\_TSC\_DelInit\(\)`](#)
- [`HAL\_TSC\_MspInit\(\)`](#)
- [`HAL\_TSC\_MspDelInit\(\)`](#)

### 67.2.4 IO Operation functions

This section provides functions allowing to:

- Start acquisition in polling mode.
- Start acquisition in interrupt mode.
- Stop conversion in polling mode.
- Stop conversion in interrupt mode.

- Poll for acquisition completed.
- Get group acquisition status.
- Get group acquisition value.

This section contains the following APIs:

- *HAL\_TSC\_Start()*
- *HAL\_TSC\_Start\_IT()*
- *HAL\_TSC\_Stop()*
- *HAL\_TSC\_Stop\_IT()*
- *HAL\_TSC\_PollForAcquisition()*
- *HAL\_TSC\_GroupGetStatus()*
- *HAL\_TSC\_GroupGetValue()*

### 67.2.5 Peripheral Control functions

This section provides functions allowing to:

- Configure TSC IOs
- Discharge TSC IOs

This section contains the following APIs:

- *HAL\_TSC\_IOConfig()*
- *HAL\_TSC\_IODischarge()*

### 67.2.6 State and Errors functions

This subsection provides functions allowing to

- Get TSC state.

This section contains the following APIs:

- *HAL\_TSC\_GetState()*

### 67.2.7 Detailed description of functions

#### **HAL\_TSC\_Init**

Function name	<b>HAL_StatusTypeDef HAL_TSC_Init (TSC_HandleTypeDef *htsc)</b>
Function description	Initialize the TSC peripheral according to the specified parameters in the TSC_InitTypeDef structure and initialize the associated handle.
Parameters	<ul style="list-style-type: none"><li>• <b>htsc:</b> TSC handle</li></ul>
Return values	<ul style="list-style-type: none"><li>• <b>HAL:</b> status</li></ul>

#### **HAL\_TSC\_DeInit**

Function name	<b>HAL_StatusTypeDef HAL_TSC_DeInit (TSC_HandleTypeDef *htsc)</b>
Function description	Deinitialize the TSC peripheral registers to their default reset values.
Parameters	<ul style="list-style-type: none"><li>• <b>htsc:</b> TSC handle</li></ul>

Return values	<ul style="list-style-type: none"> <li><b>HAL:</b> status</li> </ul>
<b>HAL_TSC_MspInit</b>	
Function name	<b>void HAL_TSC_MspInit (TSC_HandleTypeDef * htsc)</b>
Function description	Initialize the TSC MSP.
Parameters	<ul style="list-style-type: none"> <li><b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li><b>None:</b></li> </ul>
<b>HAL_TSC_MspDeInit</b>	
Function name	<b>void HAL_TSC_MspDeInit (TSC_HandleTypeDef * htsc)</b>
Function description	Deinitialize the TSC MSP.
Parameters	<ul style="list-style-type: none"> <li><b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li><b>None:</b></li> </ul>
<b>HAL_TSC_Start</b>	
Function name	<b>HAL_StatusTypeDef HAL_TSC_Start (TSC_HandleTypeDef * htsc)</b>
Function description	Start the acquisition.
Parameters	<ul style="list-style-type: none"> <li><b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li><b>HAL:</b> status</li> </ul>
<b>HAL_TSC_Start_IT</b>	
Function name	<b>HAL_StatusTypeDef HAL_TSC_Start_IT (TSC_HandleTypeDef * htsc)</b>
Function description	Start the acquisition in interrupt mode.
Parameters	<ul style="list-style-type: none"> <li><b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li><b>HAL:</b> status.</li> </ul>
<b>HAL_TSC_Stop</b>	
Function name	<b>HAL_StatusTypeDef HAL_TSC_Stop (TSC_HandleTypeDef * htsc)</b>
Function description	Stop the acquisition previously launched in polling mode.
Parameters	<ul style="list-style-type: none"> <li><b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li><b>HAL:</b> status</li> </ul>

**HAL\_TSC\_Stop\_IT**

Function name	<b>HAL_StatusTypeDef HAL_TSC_Stop_IT (TSC_HandleTypeDef * htsc)</b>
Function description	Stop the acquisition previously launched in interrupt mode.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li>• <b>HAL:</b> status</li> </ul>

**HAL\_TSC\_PollForAcquisition**

Function name	<b>HAL_StatusTypeDef HAL_TSC_PollForAcquisition (TSC_HandleTypeDef * htsc)</b>
Function description	Start acquisition and wait until completion.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li>• <b>HAL:</b> state</li> </ul>
Notes	<ul style="list-style-type: none"> <li>• There is no need of a timeout parameter as the max count error is already managed by the TSC peripheral.</li> </ul>

**HAL\_TSC\_GroupGetStatus**

Function name	<b>TSC_GroupStatusTypeDef HAL_TSC_GroupGetStatus (TSC_HandleTypeDef * htsc, uint32_t gx_index)</b>
Function description	Get the acquisition status for a group.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> <li>• <b>gx_index:</b> Index of the group</li> </ul>
Return values	<ul style="list-style-type: none"> <li>• <b>Group:</b> status</li> </ul>

**HAL\_TSC\_GroupGetValue**

Function name	<b>uint32_t HAL_TSC_GroupGetValue (TSC_HandleTypeDef * htsc, uint32_t gx_index)</b>
Function description	Get the acquisition measure for a group.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> <li>• <b>gx_index:</b> Index of the group</li> </ul>
Return values	<ul style="list-style-type: none"> <li>• <b>Acquisition:</b> measure</li> </ul>

**HAL\_TSC\_IOConfig**

Function name	<b>HAL_StatusTypeDef HAL_TSC_IOConfig (TSC_HandleTypeDef * htsc, TSC_IOConfigTypeDef * config)</b>
Function description	Configure TSC IOs.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>

- **config:** pointer to the configuration structure.
- Return values      • **HAL:** status

### **HAL\_TSC\_IODischarge**

Function name	<b>HAL_StatusTypeDef HAL_TSC_IODischarge (TSC_HandleTypeDef * htsc, uint32_t choice)</b>
Function description	Discharge TSC IOs.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> <li>• <b>choice:</b> enable or disable</li> </ul>
Return values	<ul style="list-style-type: none"> <li>• <b>HAL:</b> status</li> </ul>

### **HAL\_TSC\_GetState**

Function name	<b>HAL_TSC_StateTypeDef HAL_TSC_GetState (TSC_HandleTypeDef * htsc)</b>
Function description	Return the TSC handle state.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li>• <b>HAL:</b> state</li> </ul>

### **HAL\_TSC\_IRQHandler**

Function name	<b>void HAL_TSC_IRQHandler (TSC_HandleTypeDef * htsc)</b>
Function description	Handle TSC interrupt request.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li>• <b>None:</b></li> </ul>

### **HAL\_TSC\_ConvCpltCallback**

Function name	<b>void HAL_TSC_ConvCpltCallback (TSC_HandleTypeDef * htsc)</b>
Function description	Acquisition completed callback in non-blocking mode.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>
Return values	<ul style="list-style-type: none"> <li>• <b>None:</b></li> </ul>

### **HAL\_TSC\_ErrorCallback**

Function name	<b>void HAL_TSC_ErrorCallback (TSC_HandleTypeDef * htsc)</b>
Function description	Error callback in non-blocking mode.
Parameters	<ul style="list-style-type: none"> <li>• <b>htsc:</b> pointer to a TSC_HandleTypeDef structure that contains the configuration information for the specified TSC.</li> </ul>

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Return values

- **None:**

## 67.3 TSC Firmware driver defines

### 67.3.1 TSC

#### *Acquisition Mode*

TSC\_ACQ\_MODE\_NORMAL  
TSC\_ACQ\_MODE\_SYNCHRO

#### *CTPulse High Length*

TSC\_CTPH\_1CYCLE  
TSC\_CTPH\_2CYCLES  
TSC\_CTPH\_3CYCLES  
TSC\_CTPH\_4CYCLES  
TSC\_CTPH\_5CYCLES  
TSC\_CTPH\_6CYCLES  
TSC\_CTPH\_7CYCLES  
TSC\_CTPH\_8CYCLES  
TSC\_CTPH\_9CYCLES  
TSC\_CTPH\_10CYCLES  
TSC\_CTPH\_11CYCLES  
TSC\_CTPH\_12CYCLES  
TSC\_CTPH\_13CYCLES  
TSC\_CTPH\_14CYCLES  
TSC\_CTPH\_15CYCLES  
TSC\_CTPH\_16CYCLES

#### *CTPulse Low Length*

TSC\_CTPL\_1CYCLE  
TSC\_CTPL\_2CYCLES  
TSC\_CTPL\_3CYCLES  
TSC\_CTPL\_4CYCLES  
TSC\_CTPL\_5CYCLES  
TSC\_CTPL\_6CYCLES  
TSC\_CTPL\_7CYCLES  
TSC\_CTPL\_8CYCLES  
TSC\_CTPL\_9CYCLES  
TSC\_CTPL\_10CYCLES  
TSC\_CTPL\_11CYCLES

TSC\_CTPL\_12CYCLES  
TSC\_CTPL\_13CYCLES  
TSC\_CTPL\_14CYCLES  
TSC\_CTPL\_15CYCLES  
TSC\_CTPL\_16CYCLES

**TSC Exported Macros**

`_HAL_TSC_RESET_HANDLE_STATE`

**Description:**

- Reset TSC handle state.

**Parameters:**

- `_HANDLE_`: TSC handle

**Return value:**

- None

`_HAL_TSC_ENABLE`

**Description:**

- Enable the TSC peripheral.

**Parameters:**

- `_HANDLE_`: TSC handle

**Return value:**

- None

`_HAL_TSC_DISABLE`

**Description:**

- Disable the TSC peripheral.

**Parameters:**

- `_HANDLE_`: TSC handle

**Return value:**

- None

`_HAL_TSC_START_ACQ`

**Description:**

- Start acquisition.

**Parameters:**

- `_HANDLE_`: TSC handle

**Return value:**

- None

`_HAL_TSC_STOP_ACQ`

**Description:**

- Stop acquisition.

**Parameters:**

- `_HANDLE_`: TSC handle

**Return value:**

- None

`__HAL_TSC_SET_IODEF_OUTPPLOW`**Description:**

- Set IO default mode to output push-pull low.

**Parameters:**

- `__HANDLE__`: TSC handle

**Return value:**

- None

`__HAL_TSC_SET_IODEF_INFLOAT`**Description:**

- Set IO default mode to input floating.

**Parameters:**

- `__HANDLE__`: TSC handle

**Return value:**

- None

`__HAL_TSC_SET_SYNC_POL_FALL`**Description:**

- Set synchronization polarity to falling edge.

**Parameters:**

- `__HANDLE__`: TSC handle

**Return value:**

- None

`__HAL_TSC_SET_SYNC_POL_RISE_HIGH`**Description:**

- Set synchronization polarity to rising edge and high level.

**Parameters:**

- `__HANDLE__`: TSC handle

**Return value:**

- None

`__HAL_TSC_ENABLE_IT`**Description:**

- Enable TSC interrupt.

**Parameters:**

- `__HANDLE__`: TSC handle
- `__INTERRUPT__`: TSC interrupt

**Return value:**

- None

`__HAL_TSC_DISABLE_IT`**Description:**

- Disable TSC interrupt.

**Parameters:**

- `_HANDLE_`: TSC handle
- `_INTERRUPT_`: TSC interrupt

**Return value:**

- None

`_HAL_TSC_GET_IT_SOURCE`**Description:**

- Check whether the specified TSC interrupt source is enabled or not.

**Parameters:**

- `_HANDLE_`: TSC Handle
- `_INTERRUPT_`: TSC interrupt

**Return value:**

- SET: or RESET

`_HAL_TSC_GET_FLAG`**Description:**

- Check whether the specified TSC flag is set or not.

**Parameters:**

- `_HANDLE_`: TSC handle
- `_FLAG_`: TSC flag

**Return value:**

- SET: or RESET

`_HAL_TSC_CLEAR_FLAG`**Description:**

- Clear the TSC's pending flag.

**Parameters:**

- `_HANDLE_`: TSC handle
- `_FLAG_`: TSC flag

**Return value:**

- None

`_HAL_TSC_ENABLE_HYSTERESIS`**Description:**

- Enable schmitt trigger hysteresis on a group of IOs.

**Parameters:**

- `_HANDLE_`: TSC handle
- `_GX_IOY_MASK_`: IOs mask

**Return value:**

- None

`_HAL_TSC_DISABLE_HYSTERESIS`**Description:**

- Disable schmitt trigger hysteresis on a group of IOs.

**Parameters:**

- `__HANDLE__`: TSC handle
- `__GX_IOY_MASK__`: IOs mask

**Return value:**

- None

`__HAL_TSC_OPEN_ANALOG_SWITCH`

- Open analog switch on a group of IOs.

**Parameters:**

- `__HANDLE__`: TSC handle
- `__GX_IOY_MASK__`: IOs mask

**Return value:**

- None

`__HAL_TSC_CLOSE_ANALOG_SWITCH`

- Close analog switch on a group of IOs.

**Parameters:**

- `__HANDLE__`: TSC handle
- `__GX_IOY_MASK__`: IOs mask

**Return value:**

- None

`__HAL_TSC_ENABLE_CHANNEL`

- Enable a group of IOs in channel mode.

**Parameters:**

- `__HANDLE__`: TSC handle
- `__GX_IOY_MASK__`: IOs mask

**Return value:**

- None

`__HAL_TSC_DISABLE_CHANNEL`

- Disable a group of channel IOs.

**Parameters:**

- `__HANDLE__`: TSC handle
- `__GX_IOY_MASK__`: IOs mask

**Return value:**

- None

`__HAL_TSC_ENABLE_SAMPLING`

- Enable a group of IOs in sampling mode.

**Parameters:**

- `__HANDLE__`: TSC handle

- `__GX_IOY_MASK__`: IOs mask

**Description:**

- Disable a group of sampling IOs.

**Parameters:**

- `__HANDLE__`: TSC handle
- `__GX_IOY_MASK__`: IOs mask

**Description:**

- Enable acquisition groups.

**Parameters:**

- `__HANDLE__`: TSC handle
- `__GX_MASK__`: Groups mask

**Description:**

- Disable acquisition groups.

**Parameters:**

- `__HANDLE__`: TSC handle
- `__GX_MASK__`: Groups mask

**Description:**

- Gets acquisition group status.

**Parameters:**

- `__HANDLE__`: TSC Handle
- `__GX_INDEX__`: Group index

**Description:**

- SET: or RESET

***Flags definition***`TSC_FLAG_EOA``TSC_FLAG_MCE`***Group definition***`TSC_NB_OF_GROUPS``TSC_GROUP1`

TSC\_GROUP2  
TSC\_GROUP3  
TSC\_GROUP4  
TSC\_GROUP5  
TSC\_GROUP6  
TSC\_GROUP7  
TSC\_GROUP8  
TSC\_ALL\_GROUPS  
TSC\_GROUP1\_IDX  
TSC\_GROUP2\_IDX  
TSC\_GROUP3\_IDX  
TSC\_GROUP4\_IDX  
TSC\_GROUP5\_IDX  
TSC\_GROUP6\_IDX  
TSC\_GROUP7\_IDX  
TSC\_GROUP8\_IDX  
TSC\_GROUP1\_IO1  
TSC\_GROUP1\_IO2  
TSC\_GROUP1\_IO3  
TSC\_GROUP1\_IO4  
TSC\_GROUP1\_ALL\_IOS  
TSC\_GROUP2\_IO1  
TSC\_GROUP2\_IO2  
TSC\_GROUP2\_IO3  
TSC\_GROUP2\_IO4  
TSC\_GROUP2\_ALL\_IOS  
TSC\_GROUP3\_IO1  
TSC\_GROUP3\_IO2  
TSC\_GROUP3\_IO3  
TSC\_GROUP3\_IO4  
TSC\_GROUP3\_ALL\_IOS  
TSC\_GROUP4\_IO1  
TSC\_GROUP4\_IO2  
TSC\_GROUP4\_IO3  
TSC\_GROUP4\_IO4  
TSC\_GROUP4\_ALL\_IOS

TSC\_GROUP5\_IO1  
TSC\_GROUP5\_IO2  
TSC\_GROUP5\_IO3  
TSC\_GROUP5\_IO4  
TSC\_GROUP5\_ALL\_IOS  
TSC\_GROUP6\_IO1  
TSC\_GROUP6\_IO2  
TSC\_GROUP6\_IO3  
TSC\_GROUP6\_IO4  
TSC\_GROUP6\_ALL\_IOS  
TSC\_GROUP7\_IO1  
TSC\_GROUP7\_IO2  
TSC\_GROUP7\_IO3  
TSC\_GROUP7\_IO4  
TSC\_GROUP7\_ALL\_IOS  
TSC\_GROUP8\_IO1  
TSC\_GROUP8\_IO2  
TSC\_GROUP8\_IO3  
TSC\_GROUP8\_IO4  
TSC\_GROUP8\_ALL\_IOS  
TSC\_ALL\_GROUPS\_ALL\_IOS

***Interrupts definition***

TSC\_IT\_EOA  
TSC\_IT\_MCE

***IO Default Mode***

TSC\_IODEF\_OUT\_PP\_LOW  
TSC\_IODEF\_IN\_FLOAT

***IO Mode***

TSC\_IOMODE\_UNUSED  
TSC\_IOMODE\_CHANNEL  
TSC\_IOMODE\_SHIELD  
TSC\_IOMODE\_SAMPLING

***Max Count Value***

TSC\_MCV\_255  
TSC\_MCV\_511  
TSC\_MCV\_1023

TSC\_MCV\_2047

TSC\_MCV\_4095

TSC\_MCV\_8191

TSC\_MCV\_16383

***Pulse Generator Prescaler***

TSC\_PG\_PRESC\_DIV1

TSC\_PG\_PRESC\_DIV2

TSC\_PG\_PRESC\_DIV4

TSC\_PG\_PRESC\_DIV8

TSC\_PG\_PRESC\_DIV16

TSC\_PG\_PRESC\_DIV32

TSC\_PG\_PRESC\_DIV64

TSC\_PG\_PRESC\_DIV128

***Spread Spectrum Prescaler***

TSC\_SS\_PRESC\_DIV1

TSC\_SS\_PRESC\_DIV2

***Synchro Pin Polarity***

TSC\_SYNC\_POLARITY\_FALLING

TSC\_SYNC\_POLARITY\_RISING

## 68 HAL UART Generic Driver

### 68.1 UART Firmware driver registers structures

#### 68.1.1 UART\_InitTypeDef

##### Data Fields

- *uint32\_t BaudRate*
- *uint32\_t WordLength*
- *uint32\_t StopBits*
- *uint32\_t Parity*
- *uint32\_t Mode*
- *uint32\_t HwFlowCtl*
- *uint32\_t OverSampling*
- *uint32\_t OneBitSampling*
- *uint32\_t ClockPrescaler*

##### Field Documentation

- ***uint32\_t UART\_InitTypeDef::BaudRate***

This member configures the UART communication baud rate. The baud rate register is computed using the following formula:  $\text{UART} = \frac{\text{uart\_ker\_ckpres}}{\text{BaudRate}}$  If oversampling is 16 or in LIN mode, Baud Rate Register =  $\frac{\text{uart\_ker\_ckpres}}{\text{BaudRate}}$  If oversampling is 8, Baud Rate Register[15:4] =  $\frac{\text{uart\_ker\_ckpres}}{\text{BaudRate}}$  Baud Rate Register[3] = 0 Baud Rate Register[2:0] =  $\frac{\text{uart\_ker\_ckpres}}{\text{BaudRate}}$  LPUART: Baud Rate Register =  $\frac{\text{uart/lpuart\_ker\_ck\_pres}}{\text{BaudRate}}$  where (uart/lpuart)\_ker\_ck\_pres is the UART input clock divided by a prescaler

- ***uint32\_t UART\_InitTypeDef::WordLength***

Specifies the number of data bits transmitted or received in a frame. This parameter can be a value of [\*\*UARTEx\\_Word\\_Length\*\*](#).

- ***uint32\_t UART\_InitTypeDef::StopBits***

Specifies the number of stop bits transmitted. This parameter can be a value of [\*\*UART\\_Stop\\_Bits\*\*](#).

- ***uint32\_t UART\_InitTypeDef::Parity***

Specifies the parity mode. This parameter can be a value of [\*\*UART\\_Parity\*\*](#)

**Note:** When parity is enabled, the computed parity is inserted at the MSB position of the transmitted data (9th bit when the word length is set to 9 data bits; 8th bit when the word length is set to 8 data bits).

- ***uint32\_t UART\_InitTypeDef::Mode***

Specifies whether the Receive or Transmit mode is enabled or disabled. This parameter can be a value of [\*\*UART\\_Mode\*\*](#).

- ***uint32\_t UART\_InitTypeDef::HwFlowCtl***

Specifies whether the hardware flow control mode is enabled or disabled. This parameter can be a value of [\*\*UART\\_Hardware\\_Flow\\_Control\*\*](#).

- ***uint32\_t UART\_InitTypeDef::OverSampling***

Specifies whether the Over sampling 8 is enabled or disabled, to achieve higher speed (up to f\_PCLK/8). This parameter can be a value of [\*\*UART\\_Over\\_Sampling\*\*](#).

- ***uint32\_t UART\_InitTypeDef::OneBitSampling***

Specifies whether a single sample or three samples' majority vote is selected. Selecting the single sample method increases the receiver tolerance to clock deviations. This parameter can be a value of [\*\*UART\\_OneBit\\_Sampling\*\*](#).